Entry and exit points (1)

- Entry and exit points (Pseudostates)
 - provide better encapsulation of composite states
 - help avoid "unstructured" transitions



Entry and exit points (2)

Notational alternatives



Semantically equivalent



History states

- History states represent the last active
 - substate (shallow history), or
 - configuration (deep history)

of a region.





Metamodel



Run-to-Completion Step: Overview



- Choose an **event** from the event pool (queue)
- Choose a **maximal**, **conflict-free**, **prioritized**, set of transitions enabled by the event
- Execute set of transitions
 - exit source states (inside-out)
 - execute transition effects
 - enter target states (outside-in)

thereby generating new events and activities

- Active state configuration
 - the states the state machine currently is in
 - forms a tree
 - if a composite state is active, all its regions are active
- Least-common-ancestor (LCA) of states s_1 and s_2
 - the least region or orthogonal state (upwards) containing s_1 and s_2



bold: active state configuration



bold: LCA of states A1 and A2

- Compound transitions
 - transitions for an event are "chained" into compound transitions
 - eliminating pseudostates like junction, fork, join, entry, exit
 - this is not possible for choice pseudostates where the guard of outgoing transitions are evaluated dynamically (in contrast to junctions)
 - several source and target states





Run-to-Completion Step: Preliminaries (3)

- Main source / target state *m* of compound transition *t*
 - Let *s* be LCA of all source and target states of *t*
 - If s region: *m* = direct subvertex of *s* containing all source states of *t*
 - If *s* orthogonal state: *m* = *s*
 - Similarly for main target state
 - All states between main source and explicit source states are exited, all state between main target and explicit target states are entered.
- Conflict of compound transitions t₁ and t₂
 - intersection of states exited by t_1 and t_2 not empty
- **Priority** of compound transition t_1 over t_2
 - s_i "deepest" source state of transition t_i
 - s₁ (direct or transitive) substate of s₂

```
\mathsf{RTC}(env, conf) \equiv
  event \leftarrow fetch()
    step \leftarrow choose steps(conf, event)
    if step = \emptyset \land event \in deferred(conf)
    then defer(event)
    fi
    for transition \in step do
      conf \leftarrow handleTransition(env, conf, transition)
    od
    if isCall (event) \land event \notin deferred(conf)
    then acknowledge(event)
    fi
    conf ]
```



Run-to-Completion Step (2)

```
steps(env, conf, event) \equiv
   | transitions \leftarrow enabled(env, conf, event)
    {step | (guard, step) \in steps(conf, transitions) \land env \models guard }  \rfloor 
steps(conf, transitions) \equiv
   | steps \leftarrow \{(true, \emptyset)\}
    for transition \in transitions do
         for (guard, step) \in steps(conf, transitions \setminus \{transition\}) do
            if inConflict(conf, transition, step)
            then if higherPriority(conf, transition, step)
                  then guard \leftarrow guard \land \neg guard(transition) fi
            else step \leftarrow step \cup {transition}
                  guard \leftarrow guard \land guard(transition) fi
            steps \leftarrow steps \cup {(guard, step)} od od
    steps_
```

Run-to-Completion Step (3)

```
handleTransition(conf, transition) \equiv
  for state \in insideOut(exited(transition)) do
     uncomplete(state)
     for timer ∈ timers(state) do stopTimer(timer) od
      execute(exit(state))
     conf \leftarrow conf \setminus \{state\}
  od
  execute(effect(transition))
  for state \in outsideIn(entered(transition)) do
      execute(entry(state))
     for timer ∈ timers(state) do startTimer(timer) od
     conf \leftarrow conf \cup \{state\}
      complete(conf, state)
  od
  conf ]
```